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Advancing Decadal Predictability in North Atlantic SST and US Rainfall

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Motivations

Weather

predictions

- Increasing demand for decadal prediction system to support near-term decision-making in agriculture, energy and water management, etc.
- "Seamless" climate prediction systems, bridging gaps between weather and climate.

Decadal prediction is a challenge! Forced boundary condition problem Decadal predictions Initial value problem day week month season year decade century

Seasonal to interannual

predictions

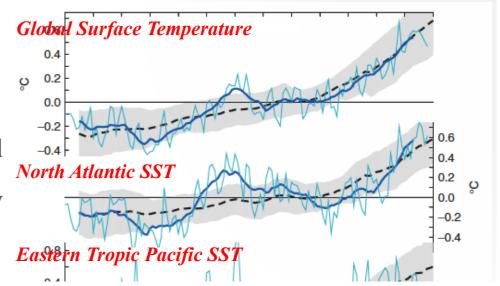
Long term climate

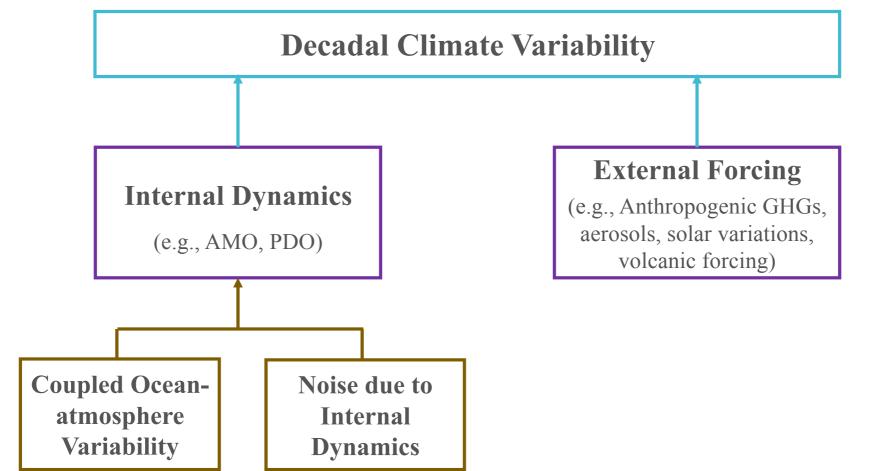
change projections



Challenges/Questions

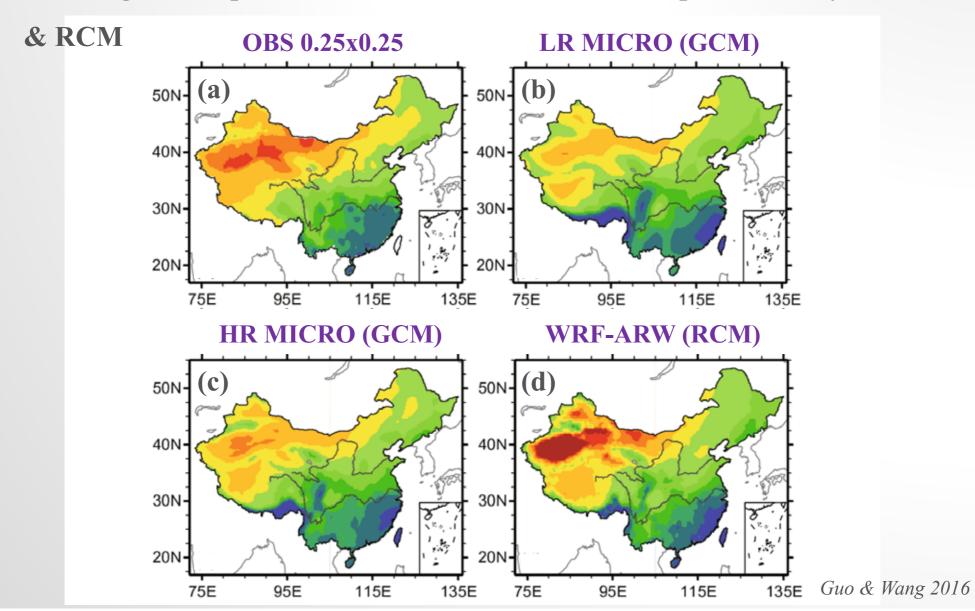
 Challenge I: Limits, sources and mechanisms of decadal predictability are not fully understood





Challenges/Questions

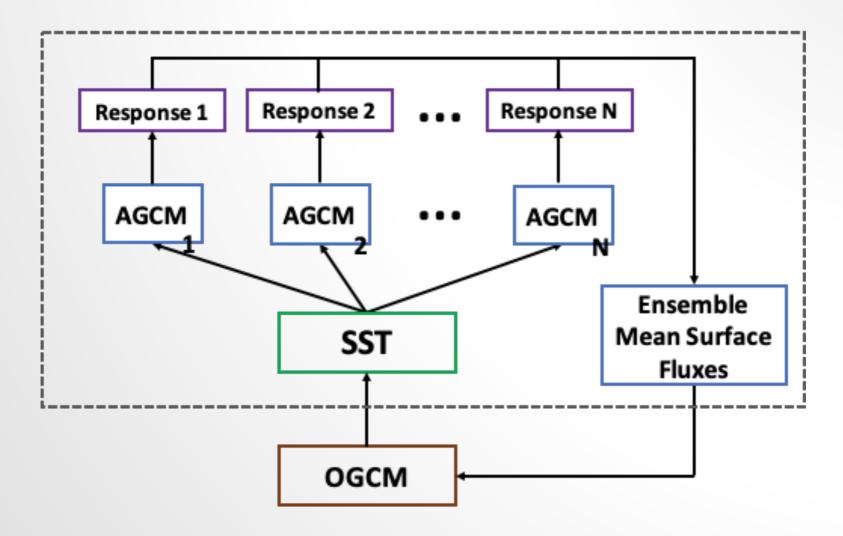
• Challenge II: Impact of model resolution on decadal predictability in GCM



GCM Experiments and RCM Simulations

GCM: CCSM4	Ocean resolution	Atmosphere resolution	Ensemble size	Simulation length (year)
Standard control eddy parameterized (LR)	1.0° Lat × 1.0° Lon (Telescoping in the tropics)	~0.5°	1	255
IE eddy parameterized (LRIE)	1.0° Lat × 1.0° Lon (Telescoping in the tropics)	~0.5°	1 ocean, 10 atmospheres	225
Standard control eddy resolving (HR)	0.1° Lat × 0.1° Lon Globally	~0.5°	4	~70
IE eddy resolving (HRIE)	0.1° Lat × 0.1° Lon Globally	~0.5°	1 ocean, 10 atmospheres	163
Driver	RCM	Resolution	Simulation length	
GFDL-ESM2M	WRF	0.44°	Historical 1950-2005 (bias-corrected)	
		0.22°		
IE:		Kirtman et al., 2017; Zhang & Kirtman 2019 GRL Accepted		

Interactive Ensemble (IE) Coupling Strategy



The basic intent of the IE is to reduce internal atmospheric noise, allowing an assessment of how noise impacts decadal predictability.

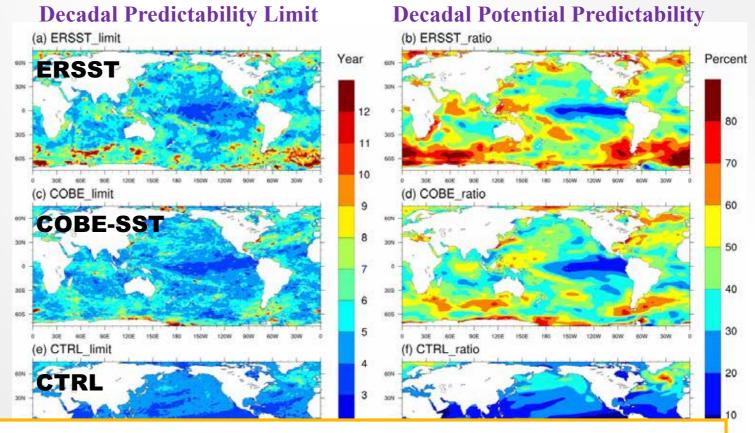
Decadal SST Predictability (LR simulations)

Limit of Predictability

Nonlinear Local Lyapunov Exponent method to find analog pairs based on error saturation theory (Ding et al., 2016)

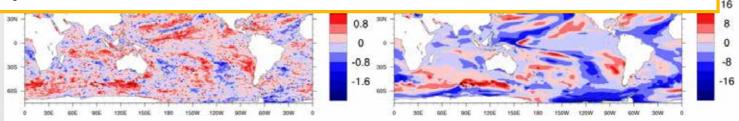
Potential Predictability:

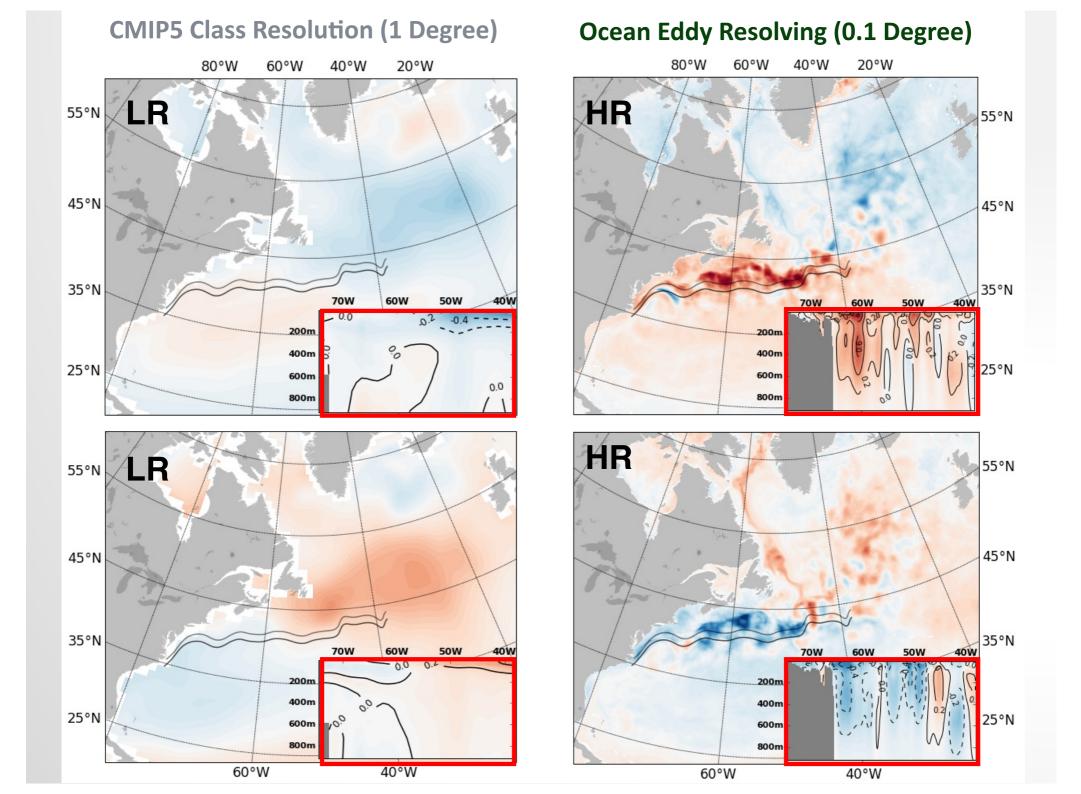
Ratio of 9-year low-pass filtered variance to the total variance (Boer, 2000)

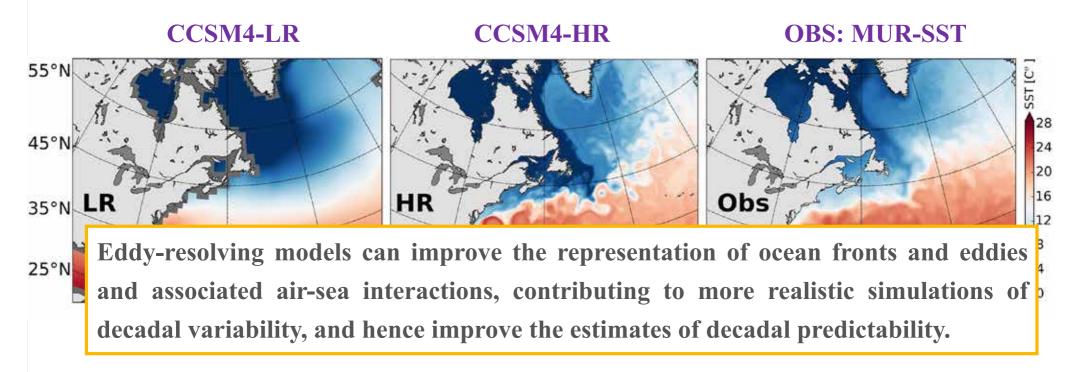


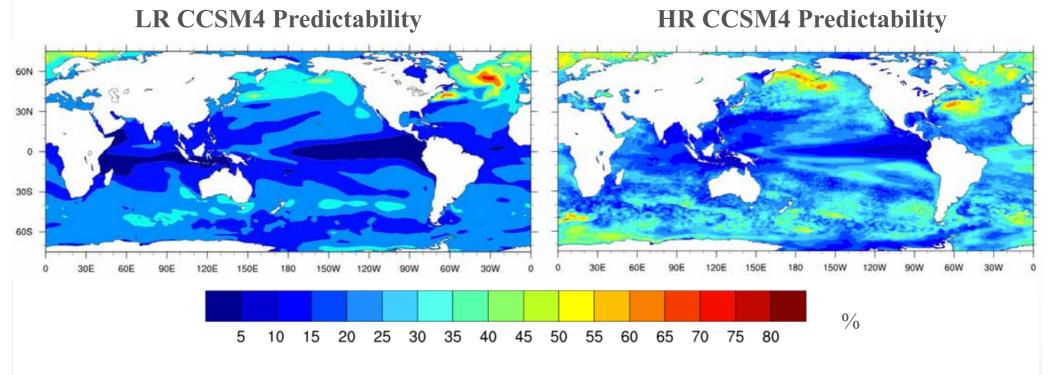
Models underestimate decadal SST predictability; reducing internal atmospheric noise may increase or decrease decadal SST predictability depending on background air-sea coupling and dynamics.

Zhang & Kirtman 2019 GRL (Research Highlight)

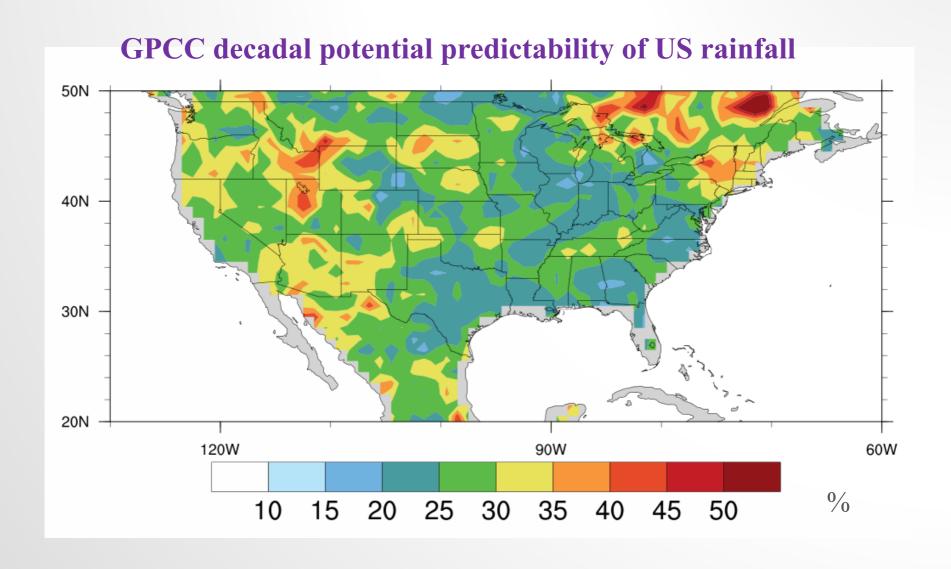


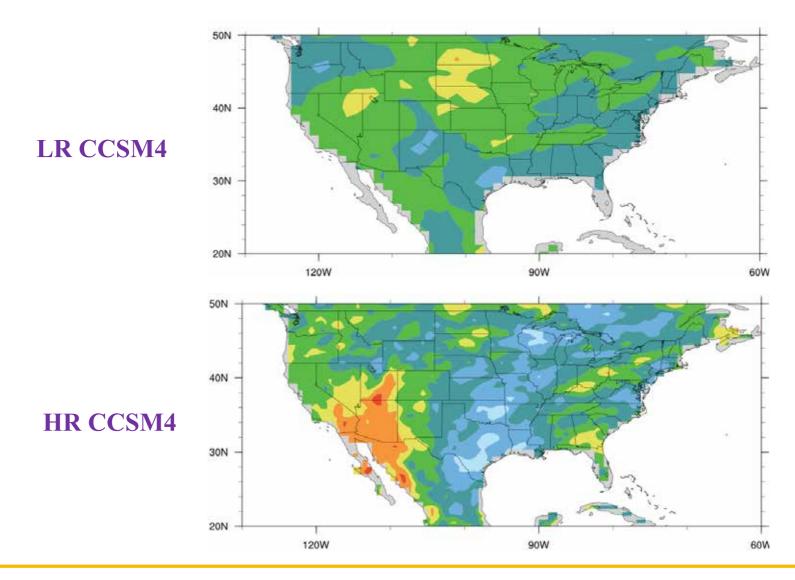




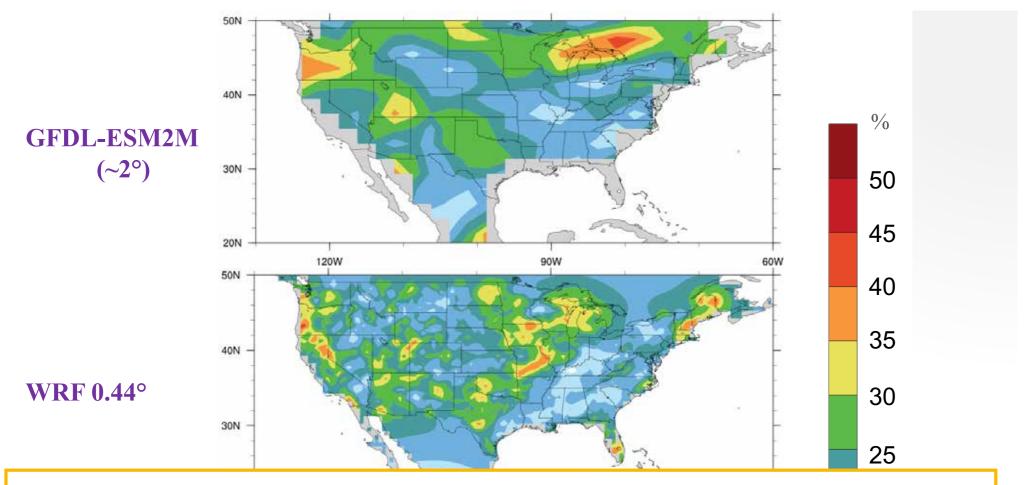


Decadal Predictability of US Rainfall

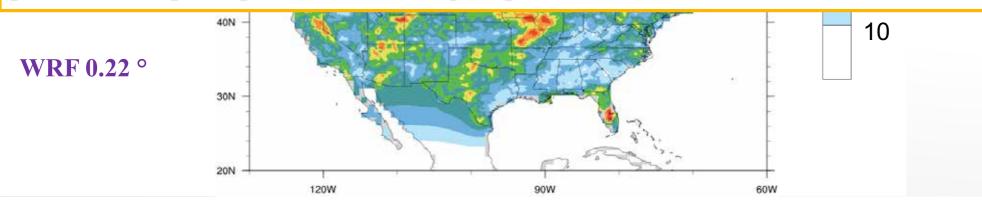




Eddy-resolving model significantly impact decadal predictability of US precipitation, suggesting the influence of resolved ocean features on precipitation over land in terms of air-sea interactions and teleconnections.



RCM driven by GCM provides more detailed information about regional precipitation variability, thus impacting decadal predictability estimates. RCM may have the potential to improve prediction skills of precipitation at decadal timescales.



Summary

- LR CCSM4 underestimates decadal SST predictability in most regions; HR CCSM4 with resolved ocean features improve the representation of decadal variability, leading to improved estimates of decadal predictability.
- Reducing internal atmospheric noise (CTRL vs IE) may increase or decrease decadal SST predictability depending on background air-sea coupling and dynamics.
- Resolved ocean features significantly impacts estimates of decadal precipitation predictability in the US. RCM provides the potential for improving decadal prediction skills of precipitation at regional scales.

References

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Thank You!

Supporting Materials

Method I: Nonlinear Local Lyapunov Exponent (NLLE) (Ding et al. 2016)

Chaotic System: Error Saturation Theory based on butterfly effect (Lorenz, 1963)



We use NLLE to estimate the limit of predictability for a variable or a time series for any time-scale.

Consider a n-D continuous-time chaotic system,

$$\frac{d\mathbf{X}(t)}{dt} = \mathbf{F}(\mathbf{X}(t))$$

Dynamics, n-D vector field

Definition of error:

$$\boldsymbol{\delta}(t) = \mathbf{X}(t) - \mathbf{X}_0(t)$$

Reference/Fiducial Trajectory

Tangent Linear Term

J(x): Jacobian matrix

Error evolution equation:

Tangent Linear Model

 \Rightarrow

$$\boldsymbol{\delta}_{\mu}(t) = \boldsymbol{\mu}(\mathbf{X}_0, t)\boldsymbol{\delta}(0)$$

Linear Propagator

Or
$$\delta_{\mu}(t) = e^{\lambda t} \delta(0)$$

Definition of Traditional Lyapunov Exponent

High-order Nonlinear Term $\frac{d}{dt}\delta = \mathbf{J}(\mathbf{x})\delta + \mathbf{G}(\mathbf{x},\delta)$

$$\delta_{\eta}(t) = \eta (\mathbf{X}_0, \delta(0), t) \delta(0)$$

Nonlinear Propagator

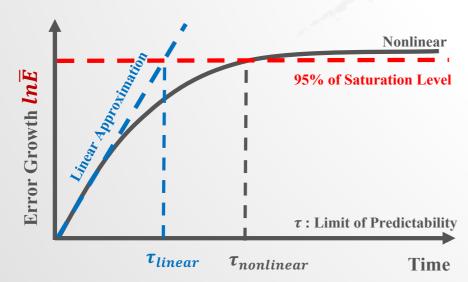
Define NLLE

$$\lambda(\mathbf{X}_0, \boldsymbol{\delta}(0), t) = \frac{1}{t} \ln \frac{\|\boldsymbol{\delta}_{\eta}(t)\|}{\|\boldsymbol{\delta}(0)\|}$$

Definition of NLLE

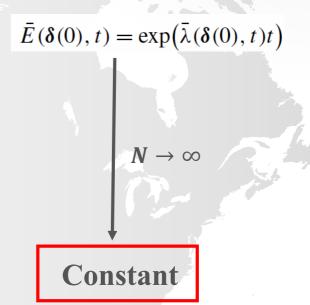
For NLLE, averaging over a lot of X₀

$$\bar{\lambda}(\delta(0), t) = \langle \lambda(\mathbf{X}_0, \delta(0), t) \rangle_N = \frac{1}{Nt} \sum_{i=1}^N \ln \frac{\| \delta_i(t) \|}{\| \delta_i(0) \|}$$



(b) Mean Error Evolution Curve for a time series

Mean relative growth of initial error



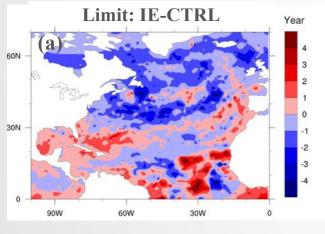
Saturation Level

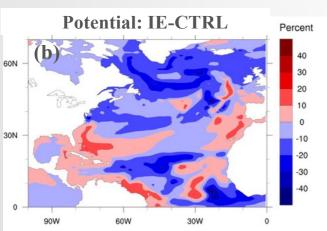
Method II: Decadal Potential Predictability (Boer, 2000)

Dedacal Timescale Ratio (DTR) =
$$\frac{Low. pass Filtered Variance}{Total Variance} \times 100\%$$

The *DTR* indicates the intensity of decadal variability, and is suggestive of the potential of decadal predictability.

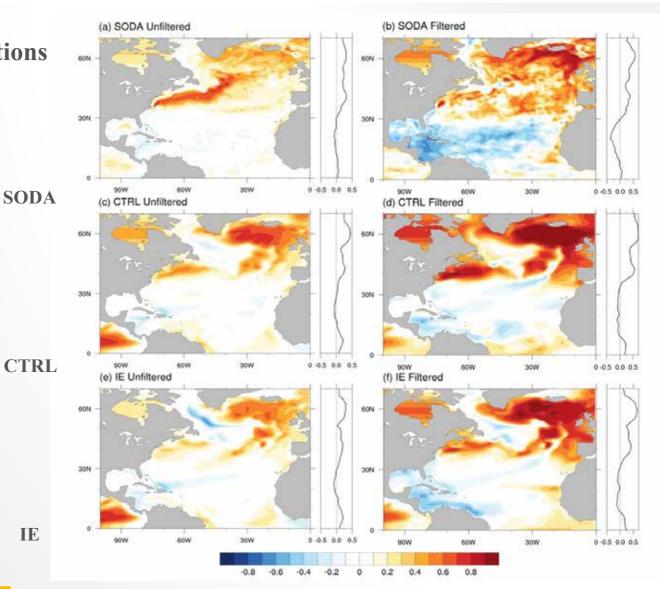
Eddy-parameterized LR Simulations





Reducing the noise decreases subsurface decadal predictability of ocean temperature especially in the subpolar regions.

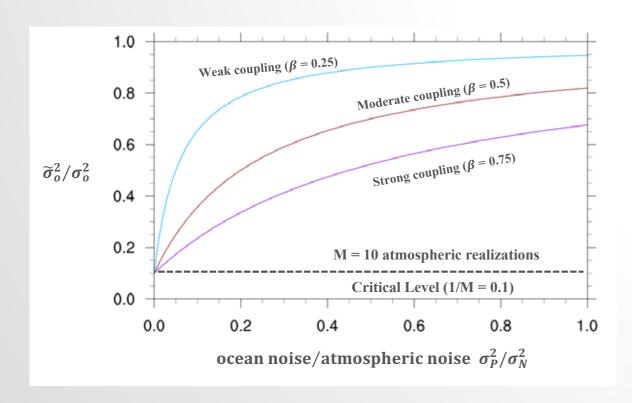
IE



LR CCSM4 simulations misrepresent the vertical connectivity between SST and subsurface ocean temperature, especially in the subtropics.

Preliminary Results

• Variance Test based on Hasselmann Hypothesis (Hasselmann, 1976)



IE/CTRL Variance Ratio (e.g., SST)

$$\frac{\tilde{\sigma}_o^2}{\sigma_o^2} = \frac{\beta^2/M + \sigma_P^2/\sigma_N^2}{\beta^2 + \sigma_P^2/\sigma_N^2}$$

$$\widetilde{\sigma}_o^2/\sigma_o^2 < 1/M \ (M=10)$$

Null hypothesis works! Totally atmospheric noise forced

$$1/M < \widetilde{\sigma}_o^2/\sigma_o^2 < 1.0$$

Either Atmospheric noise, Ocean noise or nonlinear dynamics comes into play

$$\widetilde{\sigma}_o^2/\sigma_o^2 > 1.0$$

Null hypothesis fails! Unstable coupled feedbacks or nonlinear dynamics

